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The role of shape disorder in the collective behaviour of aligned fibrous matter †

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We study the compression of bundles of aligned macroscopic fibers with intrinsic shape disorder, as found in human hair and in many other natural and man-made systems. We show by a combination of experiments, numerical simulations and theory how the statistical properties of the shapes of the fibers control the collective mechanical behaviour of the bundles. This work paves the way for designing aligned fibrous matter with purposed-designed properties from large numbers of individual strands of selected geometry and rigidity.

1 Introduction

In natural and composite bundles of nearly fully aligned fibers, as for instance in hair tresses, ponytails and other natural fagots, the spontaneously curved shapes of the individual strands allow for an intrinsic fluffiness of the materials^{1–4}. This was first discussed by Van Wyk⁵ who proposed an equation of state (EOS) for the material compressibility by suggesting that the response of wool stacks to compression is mostly controlled by the bending modes of the fiber strands. The suggestion has been widely discussed in work related to fibrous matter⁶, in explanations of the compressibility of textiles⁷, matted fibers⁸, non-woven fibrous mats, needled⁹ or not¹⁰, of bulk samples of wool fibers¹¹, for studies of the shape of hair ponytails¹², for predicting droplet formation at the tip of wet brushes¹³, or even to study the mechanical response of aegagropilae¹⁴.

Since van Wyk's seminal work⁵ many models have been proposed to understand the collective mechanical elasticity of stacks of randomly oriented straight fibers^{15–18}. Recently Broedersz *et al.* have shown that the elastic properties of such networks are governed by bending elasticity for low connectivity and by stretching elasticity for high connectivity¹⁸. In this paper, we focus on the case of highly aligned fibers with disordered shapes. The statistical mechanics nature of this challenge was first recognised by Beckrich *et al.*¹⁹ who computed the compression modulus of fiber stacks within a self-consistent mean-field treatment in two dimensions, predicting the shapes of brooms and other fluffy cones made from fibers. Here we test the validity of a statisti-

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Fig. 1 Central image: compression of a polypropylene stack and summary of the different samples (steel wool, denim and polyprolpylene fiber) investigated in this paper. Circular vignettes: zoom on a volume of typical size 1 cm. Surrounding pictures: typical shapes of individual fibers of each sample (~ 10 cm length).

cal mechanics treatment of this problem by studying both experimentally and numerically the compression behaviour of stacks of fibers with intrinsic shape disorder (see Fig.1). A generalisation of the mean field theory introduced in ¹⁹ compares well with our

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results, revealing the key statistical and mechanical factors that control the EOS of fibrous matter.

2 Materials and methods

2.1 Experimental systems



Fig. 2 (Top) Example of a fiber stack of steel wool (SW1) with typical characteristic length scales (L_x , L_y). (Bottom) Single fiber shape and definition of $\zeta_0(x)$.

Experiments were performed on 6 different fiber bundles with caracteristic sizes noted L_x, L_y and D_0 , see Fig. 2 and 3. A first class of samples was obtained by unbraiding different commercial climbing ropes of polypropylene (PP1, PP2 and PP3) and standard denim cloth (DEN). For most fiber studies, fiber bundles were formed by stacking manually a high number (hundreds or thousands) of individual fibers of the same length, ensuring a strong alignment. A second class of samples (SW1 and SW2) was obtained from standard steel wools (Gerlon®). In this case, compression experiments were directly performed on the purchased samples.

The fiber sections, as observed by optical microscopy, do not have regular shapes, and we measured the following approximate diameters: PP1 and PP2 (~ $100 \pm 20 \ \mu$ m); PP3 (~ $20 \pm 5 \ \mu$ m); DEN (~ $500 \pm 100 \ \mu$ m); SW1 (~ $200 \pm 50 \ \mu$ m) and SW2 (~ $300 \pm 100 \ \mu$ m) (see ESI section S1).

The individual mass of several fibers of each stack was measured allowing us to determine the mass per length μ . Together with the full mass of the stack, it allows us to estimate the number N of fibers per bundle and the transverse density $\rho = \sqrt{N}/L_y$ (see Table 1).

2.2 Experimental methods

Compression experiments were made using two different experimental setups.

The first one is homemade, from a precision balance used as a force sensor (Mettler Toledo®) and a motorized translation stage. This setup provides a very good resolution (accuracy, $\pm 2 \times 10^{-4}$ N) in a wide range of force (6 decades from 2×10^{-4} N to 40 N). The stiffness of the device is of the order of 10 MPa, and we have systematically corrected for scale plate displacement.

The second setup is a commercial testing system (ElectropulsTME3000 from Instron®, 10 N sensor), with a lower force range (3 decades 10^{-2} -10 N, accuracy $\pm 10^{-2}$ N) but



Fig. 3 Experimental images of a stack of thousands of fibers (PP1) before compression (top) and under a compression stress P (bottom) and definitions of D and D_0 .

a higher stiffness (\sim 100 MPa). This setup was mainly used for stress-relaxation experiments.

With both setups and for each experiment we measured the distance D_0 between the compression plates at first contact, the distance D between compression plates at each step of compression, the projected lengths L_x and L_y (see Fig. 2) and the force F. We calculated the stress $P = F/L_x L_y$ and the relative deformation that we define as D_0/D (see Fig. 3).

2.3 Theoretical description

We introduce now the theoretical models used in the following. We assume that we have a two-dimensional stack of \mathcal{N} fibers in between two hard walls separated by a distance D for a compression stress P ($D = D_0$ for P = 0). The average distance between fibers will be noted $d = D/\mathcal{N}$ (and $d_0 = D_0/\mathcal{N}$ for P = 0). Individual fiber shape deformations are associated to the bending energy given by:

$$\mathscr{H}_{\text{bend}} = \kappa/2 \sum_{n=1}^{\mathcal{N}} \int_0^{L_x} dx \left[\zeta_n''(x) - \zeta_{0,n}''(x) \right]^2 \tag{1}$$

where $\zeta_n(x)$ is the deformed shape and $\zeta_{0,n}(x)$ the function describing the spontaneous shape of fiber *n* (see Fig. 2). L_x corresponds to the chain projection on the *x* axis. The bending modulus κ is an intrinsic property of a fiber, directly related to the Young's modulus and the fiber geometry. Equation (1) is valid in the limit of small deformation gradients ($\zeta'_n \ll 1$) that is a very good approximation in the case of nearly aligned fiber stacks as

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we checked on experimental and numerical systems.

2.4 Numerical simulations



Fig. 4 Sketch of the geometry of the numerical simulations at two different compression distances. The insets show the shapes of two neighbouring fibers with the definition of the angles $\theta_{0,i}$ and θ_i between consecutive beads i - 1, i and i + 1.

Numerical simulations were performed using the steepest descent method 20 to find the equilibrium conformations of compressed fibers represented by the bead-spring model 21,22 sketched in Fig. 4 with N_b beads per fiber. Interactions between beads are modelled by an effective Hamiltonian containing three terms:

$$\mathcal{H} = \mathcal{H}_{LJ} + \mathcal{H}_{bond} + \mathcal{H}_{angle}.$$
 (2)

The first term corresponds to the truncated and shifted Lennard-Jones (LJ) potential²³ describing the repulsive interaction between non-neighboring beads

$$\mathscr{H}_{\rm LJ} = 4\varepsilon \left[(\sigma/r)^{12} - (\sigma/r)^6 \right] + \varepsilon \text{ for } r/\sigma \le 2^{1/6}, \qquad (3)$$

where $r_{i,j}$ is the distance between two monomers *i* and *j*, and σ the monomer size. The second term is the connectivity potential

between two adjacent monomers on the same fiber

$$\mathscr{H}_{\text{bond}} = \frac{k_b}{2} (r_{i,i+1} - r_0)^2,$$
 (4)

with a strong spring constant $k_b = 600\varepsilon$ and $r_0 = \sigma$ the distance between to connected beads for a non-deformed fiber. The last term is the discrete representation of eqn (1). It corresponds to the angular potential that controls the chain stiffness and spontaneous shape,

$$\mathscr{H}_{\text{angle}} = \frac{k_{\theta}}{2} \ (\theta_i - \theta_{0,i})^2, \tag{5}$$

with θ_i the angle between bonds (i-1,i) and (i,i+1) and k_{θ} the angular stiffness. The set of non-vanishing reference angles $\{\theta_{0,i}\}(i=1,...,N_b)$ between any three consecutive monomers – see Fig. 4 – are chosen such that the local fiber gradients remain much smaller than unity. Fiber shapes can thus be also described by a single-valued function $\zeta_0(x)$ which allows, in the limit of large fibers, to directly compare numerical results against continuous elastic theories with $\kappa = k_{\theta}r_0$ the bending modulus.

3 Single fiber characterization

3.1 Shape characterization

As we will see below, the spontaneous shape of the fibers $\zeta_0(x)$ is a crucial determinant of the collective mechanical behavior of the bundle. We measure $\zeta_0(x)$ for a large number (~ 50) of individual fibers and we expand $\zeta_0(x)$ on the basis of the eigenfunctions $\Phi_{q_i}(x)$ of the square Laplacian operator that describes bending curvature elasticity^{24,25} (see also the ESI section S1 for more details), $\zeta_0(x) = \sum_i \zeta_{0,q_i} \Phi_{q_i}(x)$. The corresponding spectra for average values $\langle \zeta_{0,q}^2 \rangle$ are displayed on Fig. 5. The dominant amplitudes are present for $q \leq 2 \text{ mm}^{-1}$. The dispersion of the variance spreads over 6 decades. A dominant wavelength appears very clearly for PP2, PP3 and DEN. All spectra exhibit a power law regime over two or more decades of wavenumber values. The power exponent denoted α is related to the roughness of the fiber and the prefactor of the power-law to its root mean square amplitude.

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3.2 Mechanical properties

To determine experimentally the bending modulus κ of fibers we performed two different types of experiments. The first one consists in measuring the oscillation period of a horizontal fiber (see section 3.2.1). This method is particularly suited for steel fibers (SW1 and SW2) which are sufficiently rigid. However, we have not been able to apply it to synthetic fibers (PP1, PP2, PP3 and DEN) which are too light and too sensitive to small disturbances. For these fibers we have developed an original experience of stretching, inspired by the work of Kabla and Mahadevan⁴ (see section 3.2.2).

3.2.1 Single fiber oscillations

The position of the end of a horizontal fiber is measured over time during an oscillation experiment (see Fig. 6, see also the ESI for a video). A simple Fourier transform allows precisely characterising the fundamental frequency f_0 of the system (see Fig. 6 inset),



Fig. 5 (Color online) Average spectra $\langle \zeta_{0,q}^2 \rangle$ extracted from measurements of at least 40 fibers of the 6 experimental systems, and best power law fits with exponent α (solid line) for PP1 (a), SW1 (b), SW2 (c), PP2 (d), PP3 (e) and DEN (f). The insets display typical experimental fiber shapes.

which is related to the modulus of curvature by the equation^{24,25}:

$$\kappa = 3.194 \times mL^4 f_0^2,\tag{6}$$

where m is the fiber mass and L its length.

3.2.2 Single fiber stretching experiments

To determine experimentally the bending modulus κ of softer fibers we performed stretching experiments using the same experimental set-up as for fiber stack compression. A single fiber is attached by its extremities to the scale plate and the translation stage (see the ESI for a video). At each stage of the experiment, we measure the stretching force f and a snapshot is taken whereby the total length, the projected length and the shape analysis of the fiber are calculated. To avoid creating new folding states during the preparation of the fiber, we proceed as follows. We first measure the projection length L_0 of the fiber along the average direction of the unperturbed free fiber. We then fix the fiber extremities to the experimental set-up, and impose a distance between extremities slightly smaller than L_0 . Forces and distances are then only considered for distances equal or above to L_0 .



Fig. 6 Position of the end point of a SW2 fiber during an oscillation experiment. In the inset, the spectral density (SD) obtained by a simple Fourier Transform of the signal.



Fig. 7 Shape of a PP1 fiber at different steps of a stretching experiment.

As an example, the shape of a PP1 fiber for a few steps of a stretching experiment is shown in Fig. 7.

In this example, the reference state $(f(L = L_0) = 0)$ corresponds to step 6. Steps 6 to 12 show clearly that the largest wavelengths are first unfolded, as confirmed by the spectra (see the ESI section 1), where the amplitudes of the modes $q_1 \simeq 0.5 \text{ mm}^{-1}$ and $q_2 \simeq 1.0 \text{ mm}^{-1}$ (ie $\lambda_1 = 2\pi/q_1 \simeq 12 \text{ mm}$ and $\lambda_2 = 2\pi/q_2 \simeq 6 \text{ mm}$) decreased significantly more than the other ones. Beyond step 15, the deformation is dominated by elongation. Complete mode supression is typically not attainable, the fibers breaking before becoming completely straight.

The force measured during the stretching experiment is shown in Fig. 8 as a function of the length ratio. Using the equation of state developped for an extensible fiber by Kabla and MahadePublished on 28 February 2019. Downloaded by Université de Strasbourg, Service Commun de la Documentation on 2/28/2019 3:26:23 PM

van⁴

$$\frac{L}{L_0} = 1 + \frac{f}{\mu_0} - \frac{1}{4} (1 + 2\frac{f}{\mu_0}) \sum_{q} \frac{q^6 \zeta_{0,q}^2}{(f/\kappa + q^2)^2} + \frac{\kappa}{2\mu_0} \sum_{q} \frac{q^6 \zeta_{0,q}^2}{f/\kappa + q^2},$$
(7)

it is possible to deduce the bending modulus κ (J.m) and the stretching modulus of the fiber μ_0 (N).



Fig. 8 Measured force as a function of the ratio L/L_0 for PP1, PP2, PP3 and DEN samples. Solid lines corresponds to best fits obtained using eqn (7).

Best fits of the experimental curves by eqn (7) are shown in Fig. 8 and the moduli are summarized in Table 1.

3.3 Single fiber characteristics

As a summary, we carefully characterized the shapes and the bending modulus of individual fibers of the six samples that we studied. We computed the average shape spectrum of the different samples ($\{q_i, \langle \zeta_{0,q_i}^2 \rangle\}$) and the average of the bending modulus. The results are summarised in Table 1.

Table 1 Mean value of linear mass density (μ), bending (κ) and stretching (μ_0) moduli and transerve density (ρ).

	μ (μ g.cm $^{-1}$)	$\kappa \times 10^{12}$ (J.m)	μ_0 (N)	ho (mm ⁻¹)
PP1	24 ± 1	3.2 ± 1.7	1.0 ± 0.2	1.2 ± 1
PP2	18 ± 1	3.5 ± 1.8	1.3 ± 0.2	2.5 ± 2
PP3	4.7 ± 0.5	0.43 ± 0.3	1 ± 0.2	6.8 ± 4
SW1	110 ± 2	78 ± 42	-	1.6 ± 1
SW2	610 ± 11	160 ± 70	-	0.6 ± 0.4
DEN	850 ± 10	3800 ± 3200	92± 46	1 ± 0.5

4 Mechanical properties of fiber stacks

4.1 Theoretical description

4.1.1 Ordered stacks: linear elasticity

A perfectly ordered system, consisting of a stack of sinusoidal fibers $\zeta_{0,i}(x) = d_0/2\cos(2\pi x/\lambda_i + \varphi_i)$, with $(\lambda_i = \lambda$ for all *i*, $\varphi_i = (1 - (-1)^i)\pi/2$, will be referred to as the *reference system* (ref) in the following. In such an ideal configuration, the EOS can be computed easily from the functional minimization of eqn (1) leading to

$$P_{\rm ref}^{(2\rm d)} = 192 \frac{\kappa d_0}{\lambda^4} \left(\frac{D_0 - D}{D_0}\right). \tag{8}$$

This reference model will be compared to the results of numerical simulations to validate our method.

4.1.2 Self-consistent model

The challenge for a statistical mechanical treatment of aligned fibrous systems is thus to connect the information contained in spectra such as those of Fig. 5 and the mechanical behaviour under compression stress. We follow here a two-dimensional approach first introduced in ¹⁹. Briefly, fiber shape deformations are associated to the bending energy given by eqn (1). We assume that forces between first-neighbours dominate the interaction energy, an exact assumption for excluded volume potentials in two-dimensions. Assuming a quadratic form for the interactions, with a compression modulus B(d), the effective energy can be written as:

$$\mathscr{H}_{\text{eff}} = \mathscr{H}_{\text{bend}} + \frac{B(d)}{2} \sum_{n=1}^{\mathscr{N}} \int_0^L dx \left[\zeta_{n+1}(x) - \zeta_n(x) \right]^2 .$$
(9)

By functional minimization, we deduce the equilibrium shapes of the fibers and calculate the energy density:

$$\langle e \rangle = \frac{\kappa}{2d} \sum_{q} q^4 \left(1 - \sqrt{\frac{q^4}{\frac{4B(d)}{\kappa} + q^4}} \right) \langle \zeta_{0,q}^2 \rangle$$
(10)

where *d* is the mean distance between fibers. The compression modulus B(d) has to be determined self-consistently from

$$B_{\text{self}}(d) = \partial^2 \left(d \left\langle e \right\rangle \right) / \partial d^2, \qquad (11)$$

the compressive stress given by $P_{\text{self}}^{(2d)} = -\partial \left(d \langle e \rangle \right) / \partial d$ can then be calculated using:

$$P_{\text{self}}^{(2d)}(d) = -\int_{d_0}^d B_{\text{self}}(d') \mathrm{d}d'.$$
(12)

Equation (10) is the key result of this approach, it relates the shape disorder distribution measured by $\langle \zeta_{0,q}^2 \rangle$ to the energy density of the stack through a mechanical kernel accounting for bending rigidity and fiber interactions and allowing to calculate self-consistently the state equation $P_{\text{self}}(d)$.

4.2 Experimental results

We first perform stress relaxation experiments over long times (~ 10 hours). All materials demonstrate a complex relaxation behavior, highlighting the effect of fiber rearrangement (see Fig. 9). Polymer samples (see PP1) exhibit a relaxation of almost 50% over 10 hours while steel wools relaxes only about 5% over the

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Fig. 9 (Color online) Normalised stress vs times curves for PP1 (\Box , left axis) and SW1 (\triangle , right axis) at 50% of deformation in 2s. The orange area corresponds to the duration of stress experiments (20 s) presented in Fig. 10 and 11.

same time. This is likely related to the higher friction coefficient between steel fibers compared to polymers. In all cases, it is clear from the relaxation experiments that performing the full compression experiments at high enough strain rate is important in order to avoid stress relaxation by fiber rearrangement. We have thus decided to perform compression experiments on all samples with strain rate of the order of 50 mHz (full compression experiments in less than 20 s), corresponding to a maximum stress relaxation of 10% for PP samples and less than 1% for steel wools.

Stress-relative deformation curves are given in Fig. 10 and Fig. 11. All materials exhibit a strong non linear elasticity, spreading over five decades of stress values. Using the experimentally determined spectra $\zeta_{0,q}$ and the value of κ , we apply the self-consistent model (see section 4.1.2) to interpret the compression. The whole method is illustrated in Fig. 10 in the case of the sample (SW1).

We assume that the stacks of fibers consist of the transverse sum of independent planes of effective density ρ , that can be estimated from the geometrical characteristics of the bundle (see Table 1). Since all planes contribute with $P^{(2d)}(D)$ to the total stress $P^{(3d)}(D)$, we write

$$P^{(3d)}(D) = \rho P^{(2d)}(D).$$
(13)

For very weak relative deformations $(D_0/D \sim 1)$, we observe a linear behavior corresponding to the deformation of the largest wavelength λ_{max} . This linear elasticity is well described by $P_{\text{Ref}}^{(3d)} = \rho P_{\text{Ref}}^{(2d)}$, where $P_{\text{Ref}}^{(2d)}$ is given by eqn (8), and represented by dotted line in Fig. 10 and 11.

For larger relative deformations $(D_0/D \gg 1)$, we test the predictive power of eqn (10) by solving numerically the self-consistent eqn (11) for the experimentally determined distributions $\langle \zeta_{0,a}^2 \rangle$.



Fig. 10 Experimentally determined compression stress *P* vs relative deformation D_0/D for SW1 stack (\triangle). Dashed-dotted line represents the discrete self-consistent theory $\rho P_{\text{self}}^{(2d)}$ using the experimentally determined spectrum, the dashed line the corrected discrete self-consistent theory $\rho \Phi_{\text{exp}} P_{\text{self}}^{(2d)}$, the dotted line the linear elasticity behavior P_{ref} and the solid line the total stress P_{tot} (eqn (14)).

As a result we obtain the 2d-stress $P_{\text{self}}^{(2d)}(D)$ and $P_{\text{self}}^{(3d)} = \rho P_{\text{self}}^{(2d)}(D)$ that is represented as dotted-dashed lines in Fig. 10 for SW1. If the overall shape of the data is well described by the theory, it is clear that it is necessary to introduce a scaling factor Φ_{exp} to be able to reproduce the data for large deformation (see dashed line).

Finally, we calculate the total stress :

$$P_{\text{tot}}(D) = \rho \left(P_{\text{Ref}}^{(2d)}(D) + \Phi_{\text{exp}} P_{\text{self}}^{(2d)}(D) \right).$$
(14)

where Φ_{exp} is the only fitting parameters. $P_{tot}(D)$ is represented as a solid line in Fig. 10.

The experimentally determined compression stress P and the theoretical analysis for the six experimental fiber stacks studied in the paper are given in Fig. 11 with same convention as for Fig. 10. For all studied samples, we observe a very good agreement between the three-dimensional experimental compression curves and the theoretical description.

4.3 Numerical simulations

To further understand how fiber shape disorder determines the compression of the stack, we performed numerical simulations on 2-dimensional systems. We investigated three classes of twodimensional disordered systems. In this configuration, fiber rearrangements are forbidden. First, in order to validate our simulation method, we consider a stack of perfectly ordered sinusoidal fibers referred to as the *reference system* (ref) in the following (see Fig. 12 top inset). As a second step, we introduce phase disorder to the system by choosing a random phase shift φ_i homogeneously distributed in phase space $\varphi_i \in [0, 2\pi]$, referred to

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(C)

(d)

(e)

10¹



Fig. 11 Experimentally determined compression stress P vs relative deformation D_0/D for the six experimental fiber stacks studied in the paper: PP1 (□); PP2 (■); PP3 (▲); DEN (•); SW1 (△); SW2 (○). Dashed lines represent the discrete self-consistent theory $P_{\rm self}^{(3d)}$ using experimentally determined spectrum, dotted line the linear elasticity behavior $P_{ref}^{(3d)}$ and solid line the total stress $P_{tot}(D)$.

as single mode disordered systems (SMD). Finally, we investigate fiber stacks with a power-law disorder (PLD), inspired by the features of the experimentally measured distributions (Fig. 5). This allowed us, by varying the exponent α between 2 and 5, to test the self-consistent model by exploring a range of disorder wider than that of the experimental systems.

4.3.1 Reference system (ref)

Numerical simulation for the reference system is shown in Fig. 12 as (*) (see the ESI section S2 for more results). It exhibits linear elasticity, and the EOS is well described in a large compression range, without any fitting parameter, by eqn (8). At very high compressions, the fibers are fully squeezed and the stress is dominated by local excluded volume effects leading to a strong increase well above the bending contribution.

4.3.2 Single mode disorder systems (SMD)

Numerical simulations on disordered systems (SMD) distinctly exhibit non-linear elastic behavior (see Fig. 12). The compres-



Fig. 12 (Color online) Numerical simulations for Ref and SMD and using $\kappa = 2000\varepsilon$: (*) normalized stress vs relative deformation D_0/D for reference system and (dashed line) linear theory Pref without any fitting parameter; (•) SMD systems with $\delta \lambda^2 = 0.01$ and (solid line) eqn (15) (see the ESI).

sion behaviour is determined by randomness of phase shift, and the distribution of wavelengths plays only a minor role as shown in the ESI section S2. A simple analytical approach accounting for phase disorder for a sinusoidal spontaneous shape of wavelength λ and amplitude D_0 allows calculating the normalized stress as

$$\frac{P^{(2d)}\lambda^4}{192\kappa D_0} = 2\int_0^{u_{max}} \frac{(1+\cos{(2\pi u)}-D/D_0)}{(1-2u)^4(1+4u)^2} du$$
(15)

where $2\pi u_{max} = \arccos(D/D_0 - 1)$. Numerical simulation data is well described by eqn (15) without any fitting parameters. We also show in the ESI (section S2) numerical results for different fiber systems covering a range of parameters κ , λ and D_0 .

4.3.3 Power-law disorder system (PLD): numerical simulations

Finally, we investigate fiber stacks with a power-law disorder (PLD), where the amplitude $\zeta_{0,q}$ of each mode follows a Gaussian probability distribution with mean square amplitudes

$$\langle \zeta_{0,q_k}^2 \rangle = \langle \zeta_0^2 \rangle \left(\frac{\pi}{Lq_k}\right)^{\alpha} \zeta \left(\alpha, k_{min} + 3/2\right)^{-1}, \tag{16}$$

with $q_k = \{q_{k_{min}}, ..., q_{k_{Max}}\}$ $(k = \{k_{min}, ..., k_{Max}\})$ and where $\zeta(\alpha, k_{min} + 3/2)$ is the generalised zeta function²⁶. Spectra are shown for different values of α in Fig. 14. To avoid perfect stacking of fibers, we removed the first long wave-length mode $q < q_{k_{min}}$.

Fig. 14 displays compression results for the PLD cases in the normalized stress units $P_{2d}L^4/\kappa \langle \zeta_0^2 \rangle^{1/2}$ as a function of the normalized density $\langle \zeta_0^2 \rangle^{1/2} / D$, for $\alpha = 2$ and 5 (see also ESI section S2 for a more extensive set of α values). For the large density limit, where fibers are in close contact and where shape disorder is irrelevant, the data collapses on the same master curve, simi-

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Fig. 13 (Color online) Amplitude $\zeta_{0,q}$ vs q for PLD systems for $\alpha = 2$ (\Diamond), $\alpha = 3.5$ (\circ) and $\alpha = 5$ (\Box). Also shown numerical typical fiber shapes.

larly to those of a single mode fiber – see Fig. 12. For the most significant compression regime, at intermediate densities, we observe a strong dependence of the compression law on the value of the exponent α , further confirming that the mechanical properties of the macroscopic stacks are controlled by fiber disorder.

By following a procedure similar to that applied to fit the experimental results, we solve numerically the self-consistent relation eqn (11) for the numerical distributions $\langle \zeta_{0,q}^2 \rangle$. Theoretical self-consistent results, presented in Fig. 14 show a remarkable agreement with compression values from numerical simulations. The low compression regime is again well described by the linear elasticity $P_{\rm ref}^{(2d)}$ without any fitting parameters. The self-consistent theory is in good agreement with the experimental data for high compression rates, especially for very rough fibers ($\alpha < 4$), provided that a global multiplication factor $\Phi_{\rm num}$ be applied as for experimental results.

5 Discussion

Both for experimental and numerical studies, systematic deviations between the mean-field predictions and the simulations can be seen in the low relative deformation limit, where the distance between fibers is of the order of the fibers mean-square amplitude. Mean-field theory poorly describes this limit, because of the vanishing number of fibers of mean amplitude larger than $\langle \zeta_0^2 \rangle^{1/2}$. This regime can be qualitatively understood by noticing that, as the force rises sharply from zero, due to fiber-fiber contacts, it progressively builds up with essentially single-mode compression behavior. This is shown in Fig. 11 and 14, where the dashed line corresponds to the single mode expression $P_{\rm ref}$ with the wavelength λ associated to the first mode of the distribution.

At larger relative deformations, in both experimental and numerical cases, the self-consistent theory correctly described our results up to a numerical scaling factor (Φ_{exp} and Φ_{num} respectively). In both cases, these are the unique fitting parameters that we introduce in the description.



Fig. 14 (Color online) Normalized stress vs $\langle \zeta_0^2 \rangle^{1/2}/d$ from numerical simulations for PLD systems for $\alpha = 2$ (\Diamond) and $\alpha = 5$ (\Box) and using $\kappa = 2000\varepsilon$. Dashed lines represent the discrete self-consistent theory P_{self} using numerical spectrum, dotted line the linear elasticity behavior P_{ref} and solid line the total stress $P_{\text{tot}} = P_{\text{ref}}$. In inset same figure where lines represent the total stress obtained by adding the discrete self-consistent theory using numerical spectrum and the linear elasticity P_{ref} for all α .

Fig. 15 displays Φ_{num} and Φ_{exp} as a function of α . Values for both coefficients are comparable to the experimental uncertainties. This clearly demonstrates that this coefficient is not related to experimental artifacts, further supporting that our 2 dimensional approach is also relevant to describe 3-dimensional experiments up to a consistent density of stress planes ρ , and that it is the self-consistent approximation that is involved. It is worth noting that the agreement between numerical simulations and self-consistent theory is optimal for $\alpha \sim 2$, where Φ_{num} is of order unit. This is further supported by the analytical resolution of the self consistent theory in continuous limit (see ESI, section S3). This corresponds to the case of the rougher fibers with the highest number of contacts, a situation where the mean-field selfconsistent approximation is expected to be more accurate. The experimental fibers in this work have α values close to 2.8-3, were Φ is quite large. In future work, it will be interesting to identify classes of experimental fibers with $\alpha \sim 2$. It is also important to note that in our theoretical analysis and computer simulations all the fibers interactions are purely repulsive. In practice, environmental conditions such as humidity might add short range adhesive components (for instance capillary bridges) to the force between fibers. Without including drastic changes such as that from the long-range interactions in needled non-woven materials⁹, these short-range effects are nevertheless worth investigating in the future for their relevance for the compression of experimental systems such as lacquered hair with cross-linked contact points. Note that short-range attractions would also provide for material cohesion of the stacks, enabling for instance to perform tensile transversal experiments, an experimental geometry better described by approaches for nonwoven fibrous mats¹⁰.

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Fig. 15 (Color online) Normalization factors from the numerical simulations Φ_{num} (*) and the experimental studies Φ_{exp} : PP1 (\Box); PP2 (\blacksquare); PP3 (\blacktriangle); DEN (\bullet); SW1 (\triangle); SW2 (\bigcirc).

6 Conclusions

In summary we have investigated experimentally the mechanical properties of well aligned corrugated fiber stacks, showing that such fiber stacks display a strongly non-linear elastic behavior over 5-decades of stress. We showed that a theoretical self-consistent description¹⁹ connecting fiber shape disorder with stack compressibility explains well three different classes of fibers. We also performed numerical simulation studies for a larger class of fiber disorder. Interestingly we found that fiber shape, as characterized by the phase and wavelength disorder at fixed amplitude, is enough to induce a non-trivial compression behavior. We also simulated more realistic distributions for fiber disorder, with the spontaneous fiber shapes reconstituted from a superimposition of modes with power-law q-dependent amplitudes. For fibers of moderate corrugation the compression forces compare very well with our 2-dimensional mean-field theory. While more extensive simulation on 3-dimensional systems will certainly allow to better probe Van Wyk's seminal intuition⁵, our results here show that bending disorder indeed control the compressive behavior of aligned fibrous matter provided that the statistical nature of the fiber shape disorder is accounted for.

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We show how bending rigidity and shape disorder

control the mechanical properties of fiber bundles.

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